

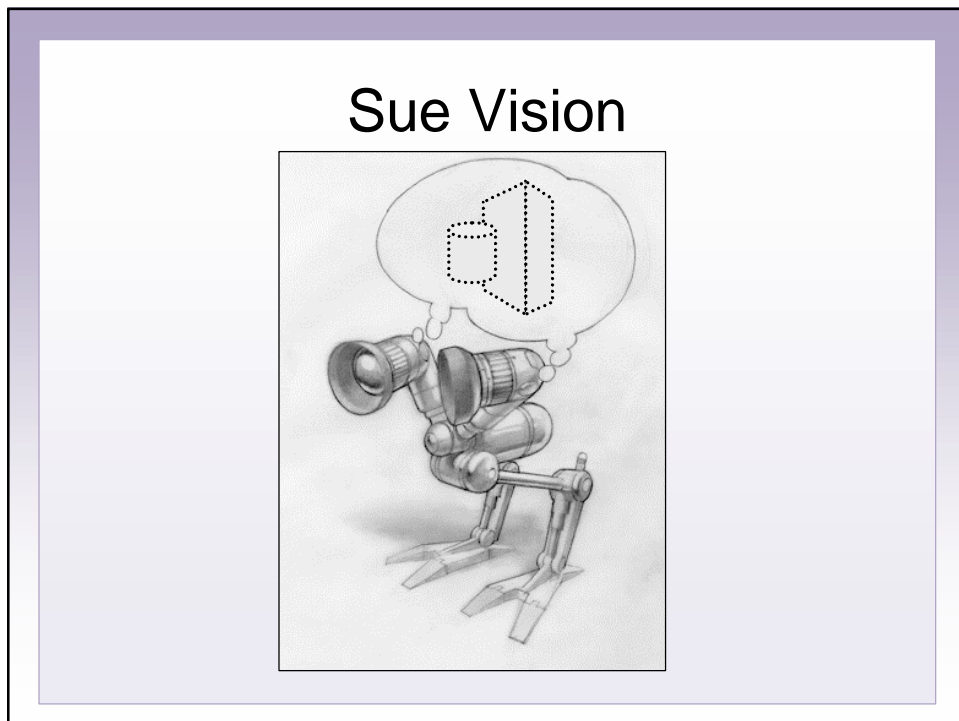
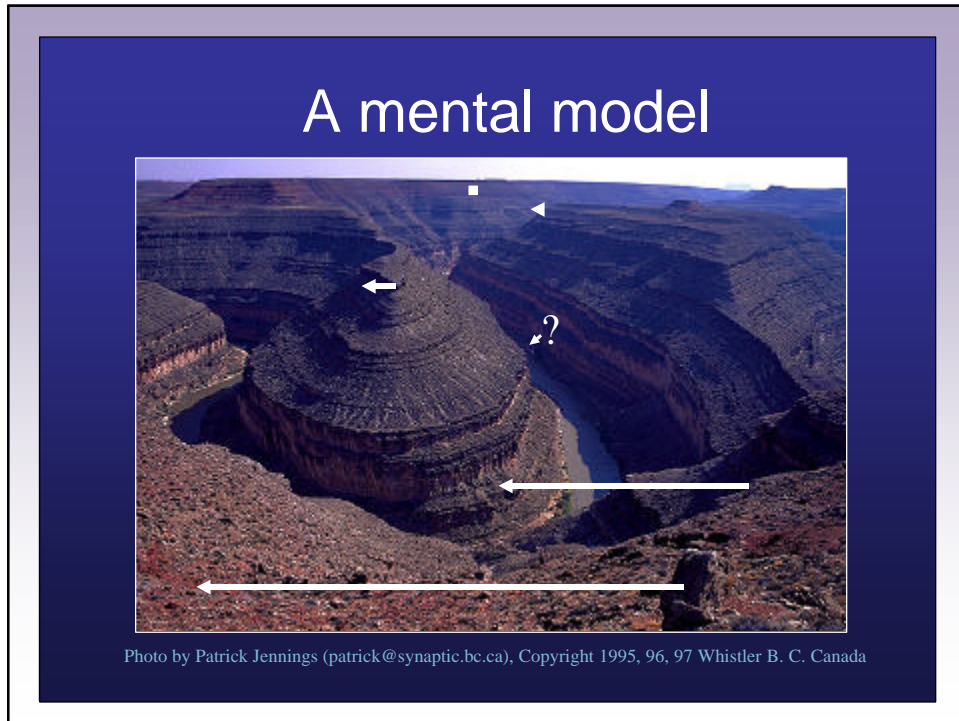
Image or Object?

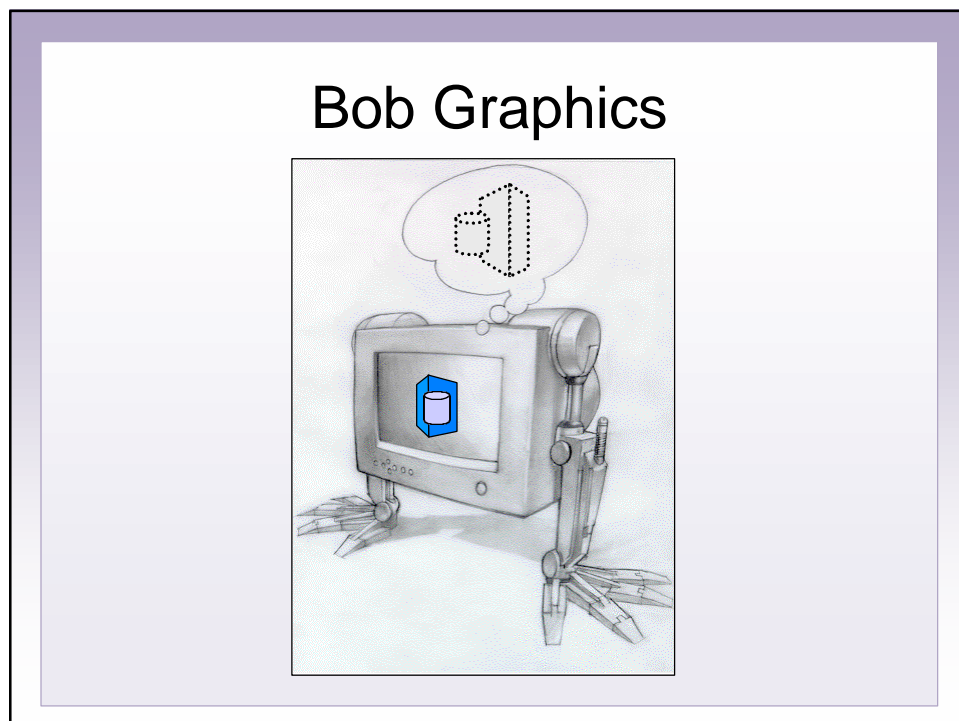
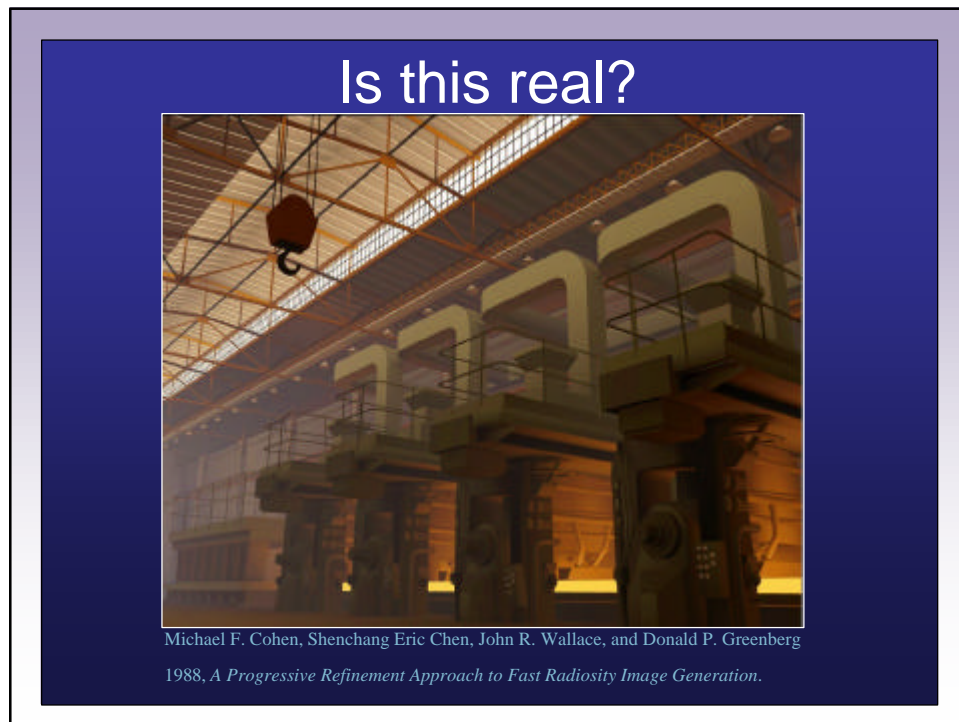
Michael F. Cohen
Microsoft Research

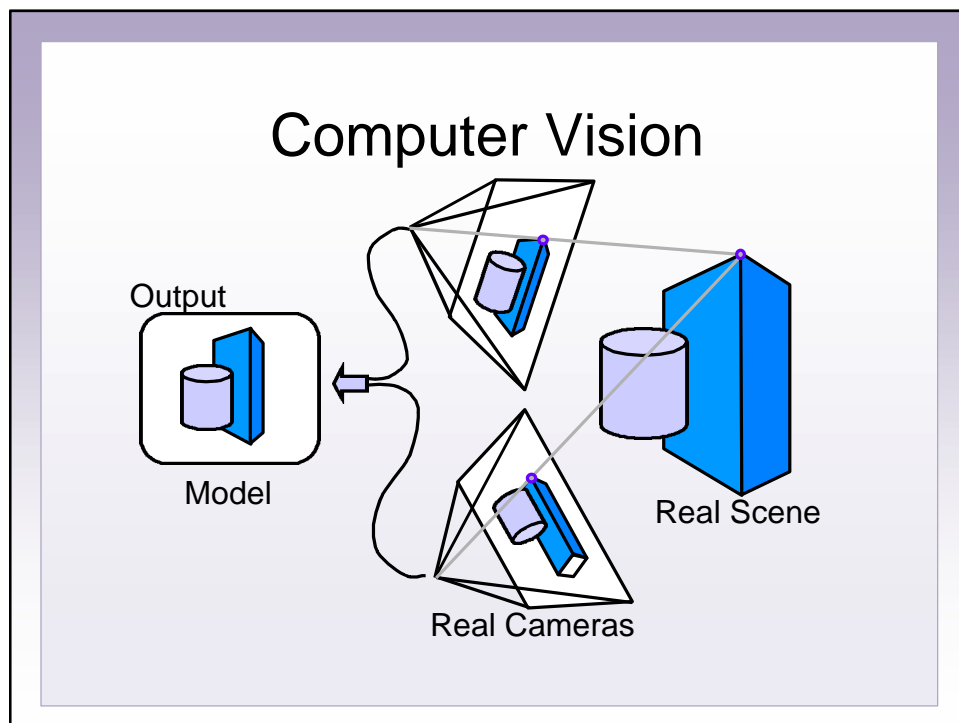
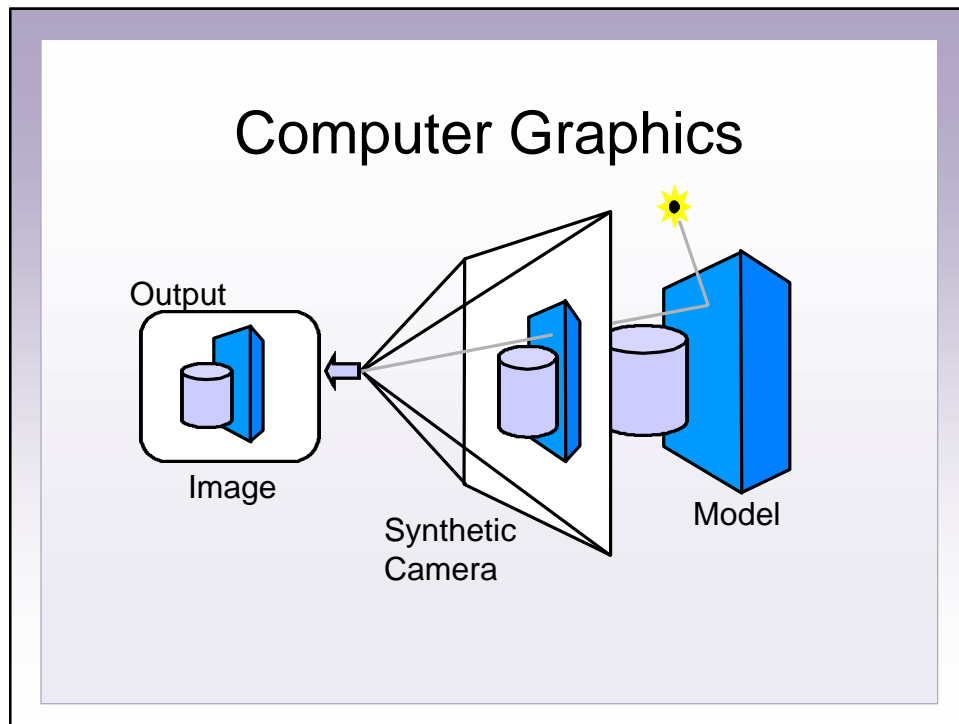
Is this real?



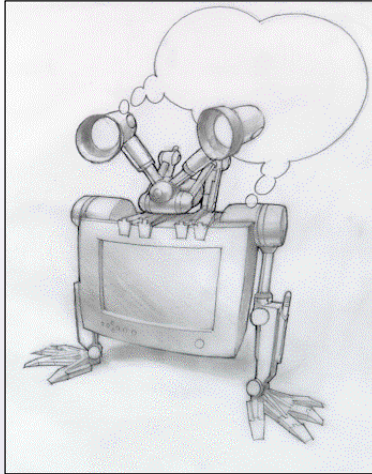
Photo by Patrick Jennings (patrick@synaptic.bc.ca), Copyright 1995, 96, 97 Whistler B. C. Canada



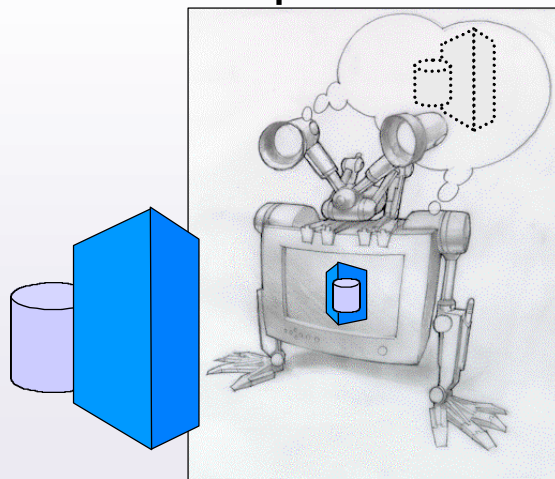


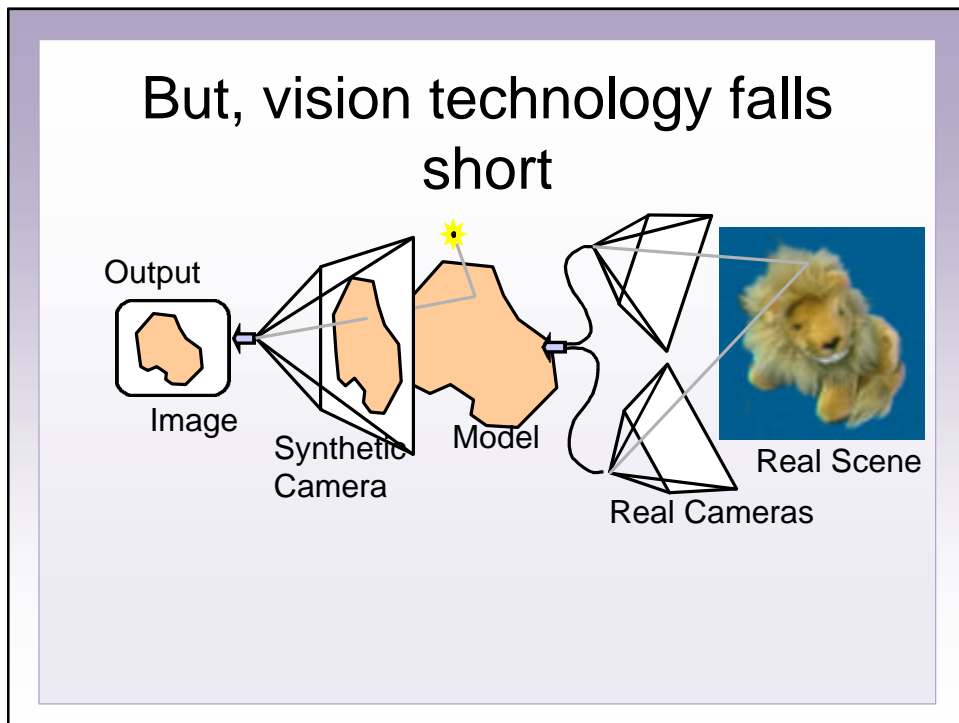
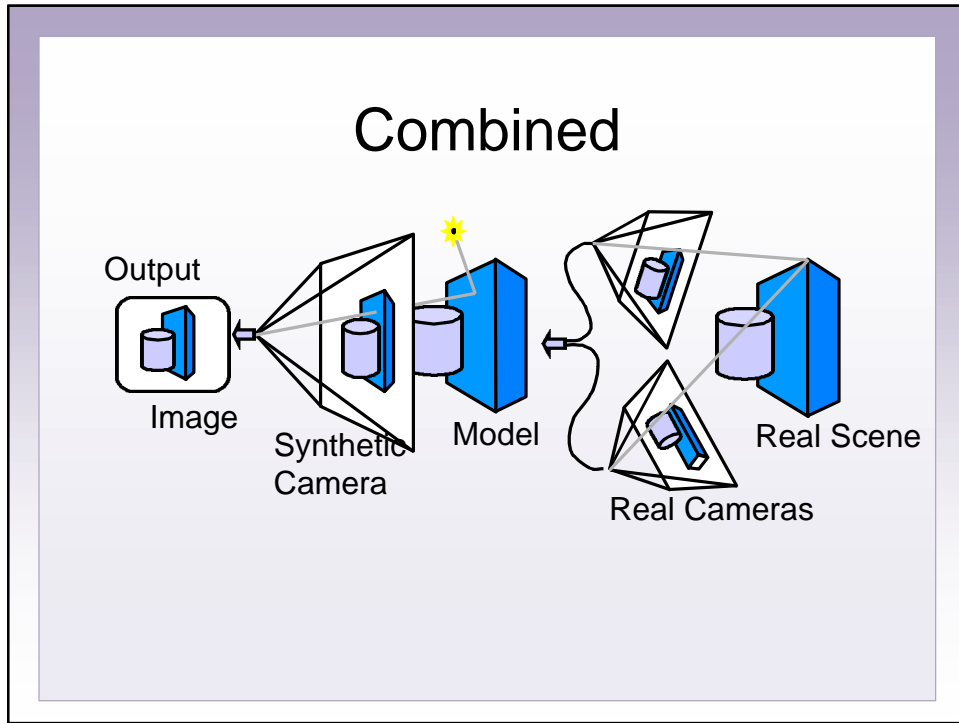


Computer Graphics Meets Computer Vision



Computer Graphics Meets Computer Vision





... and so does graphics.

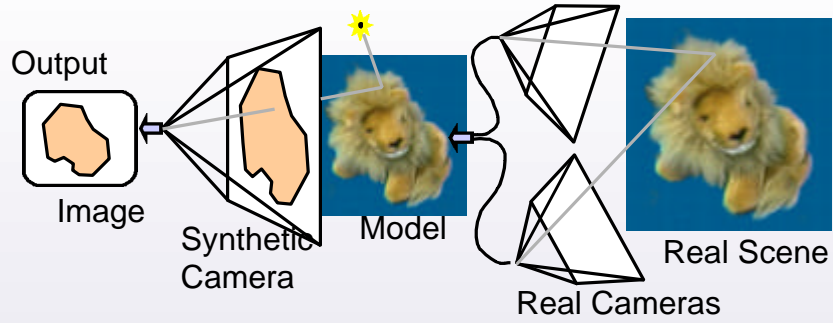
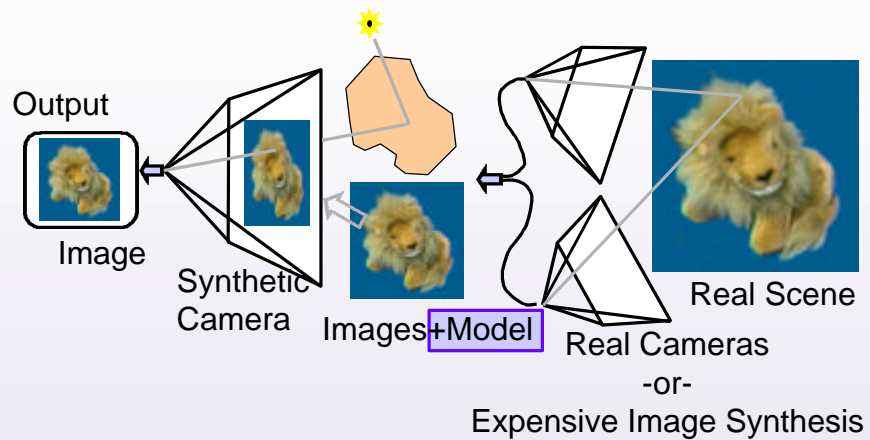
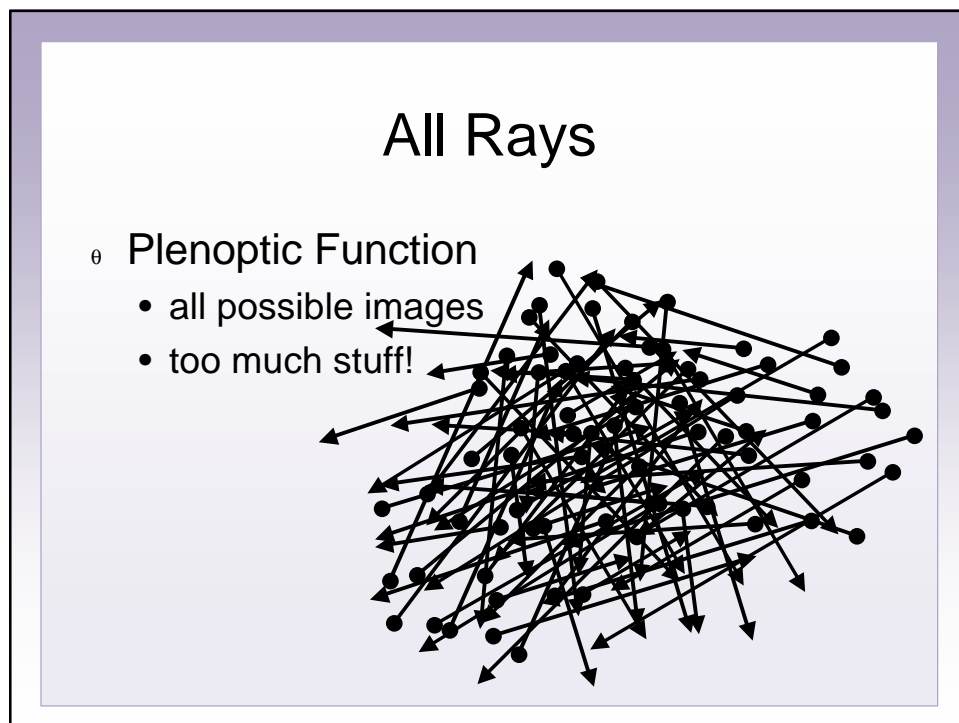
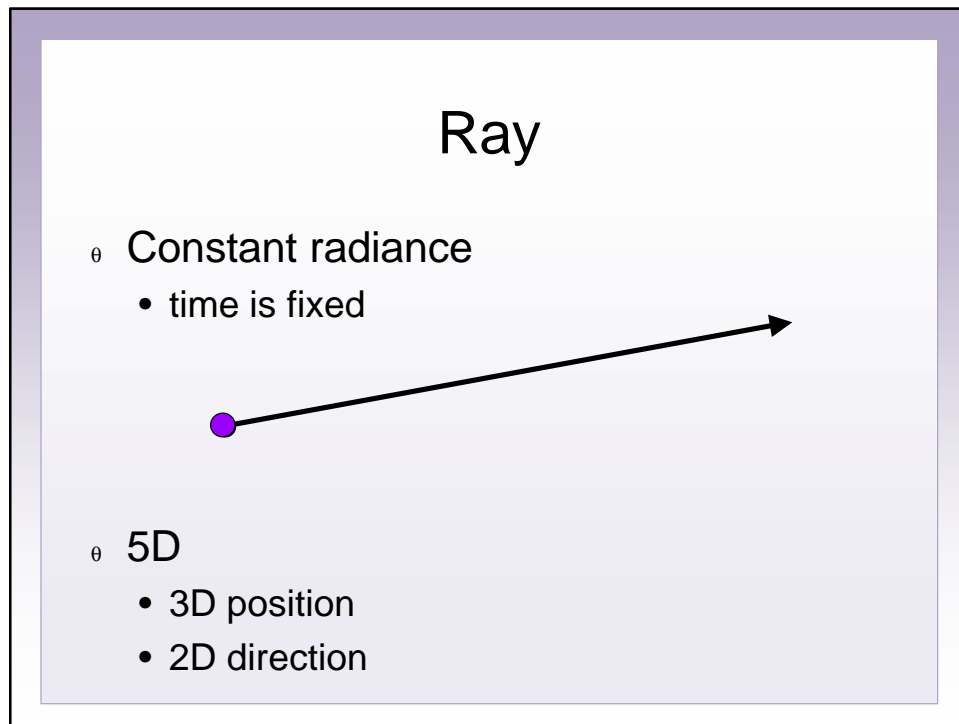
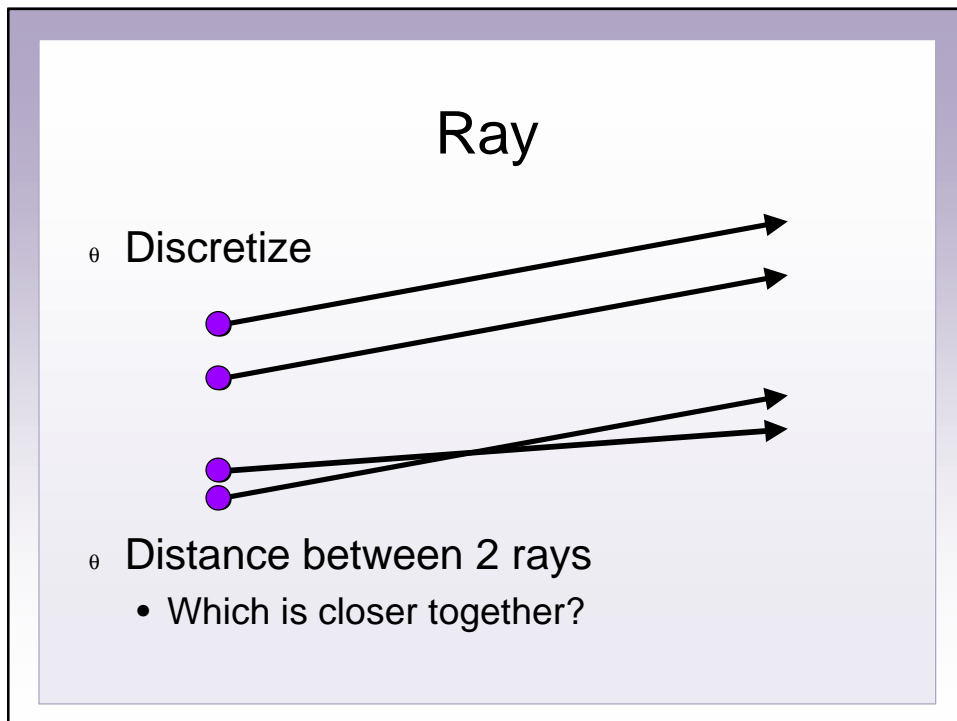
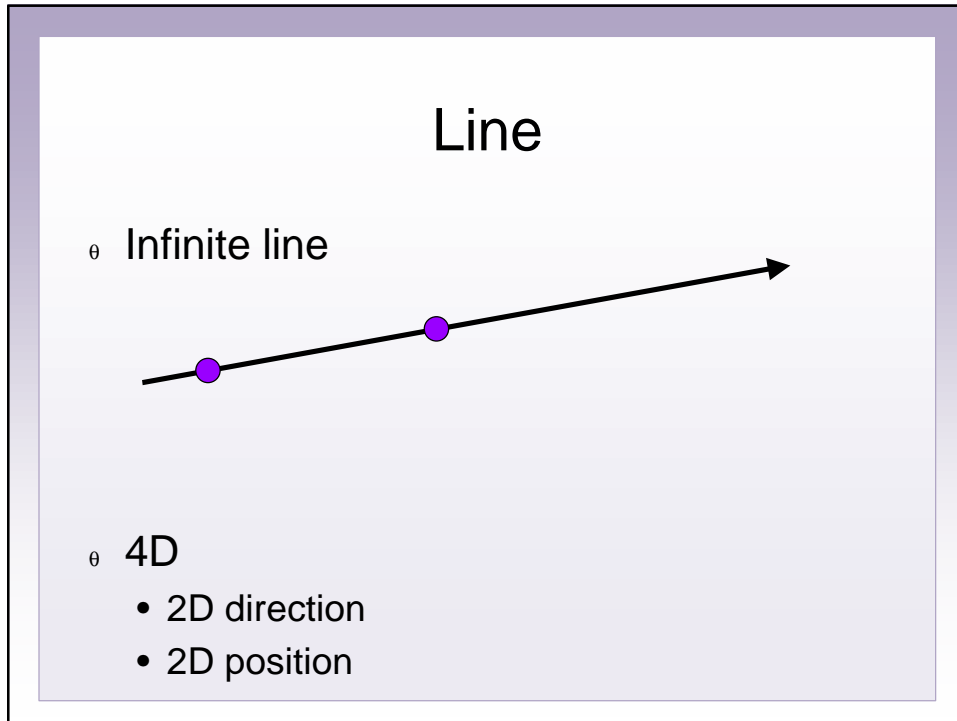
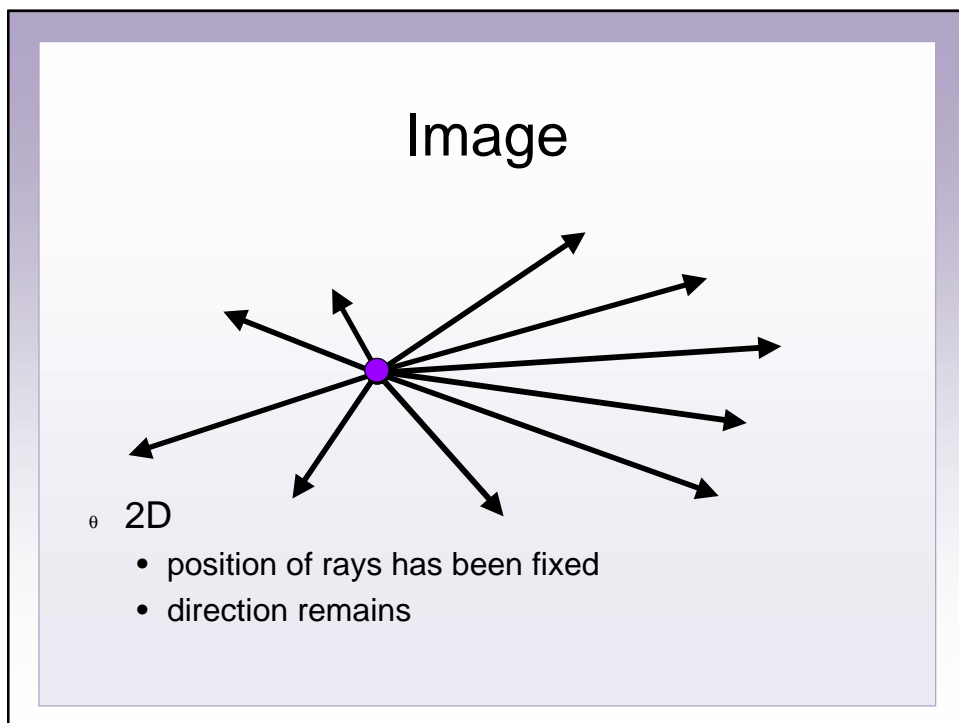
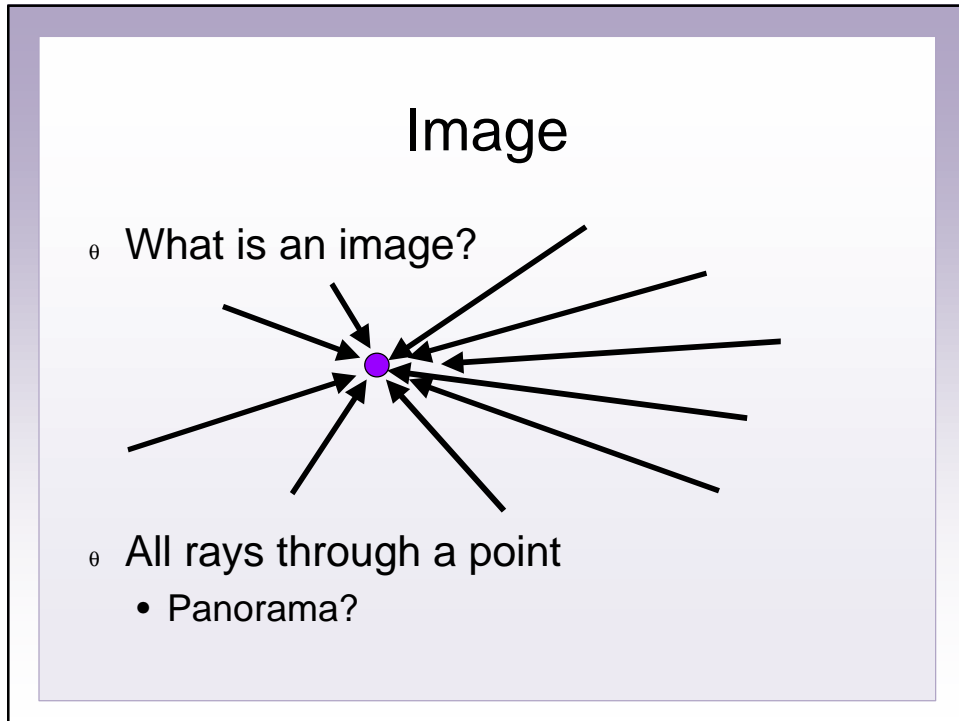


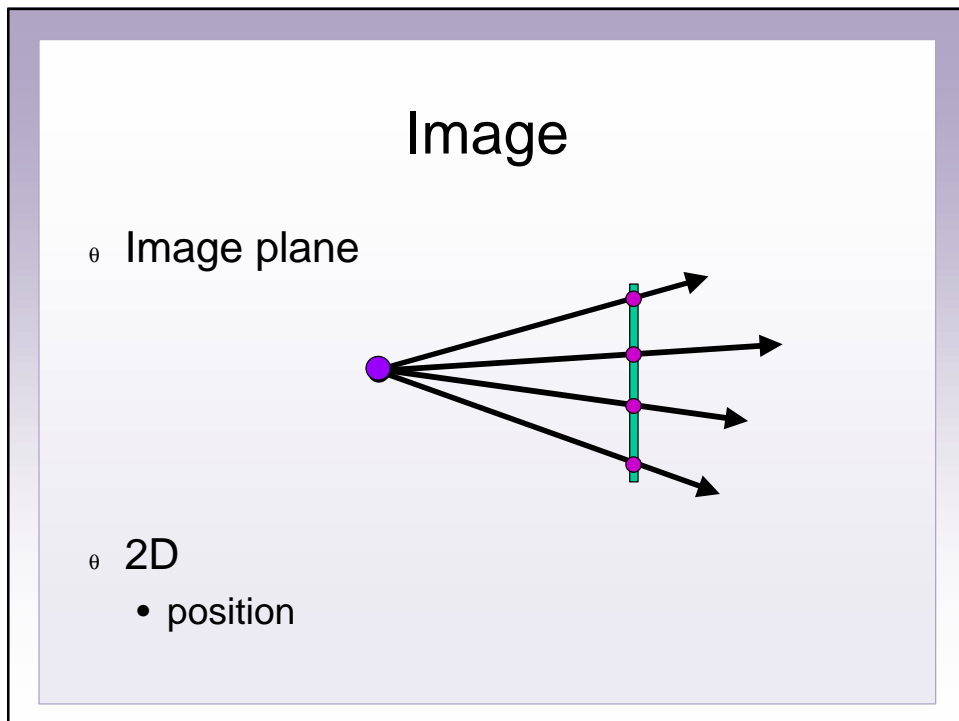
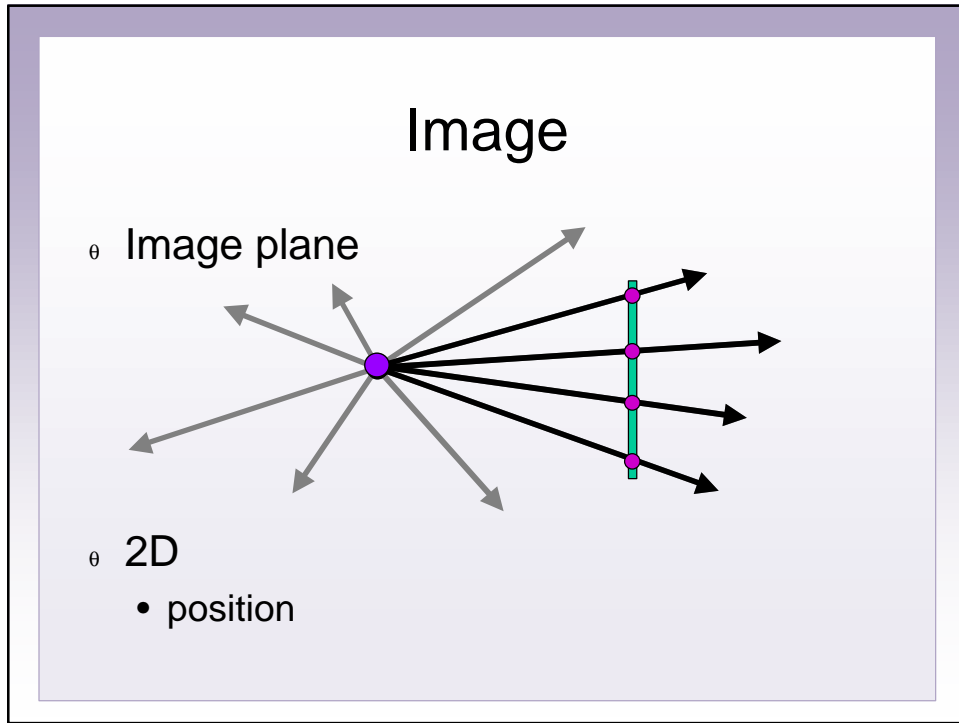
Image Based Rendering

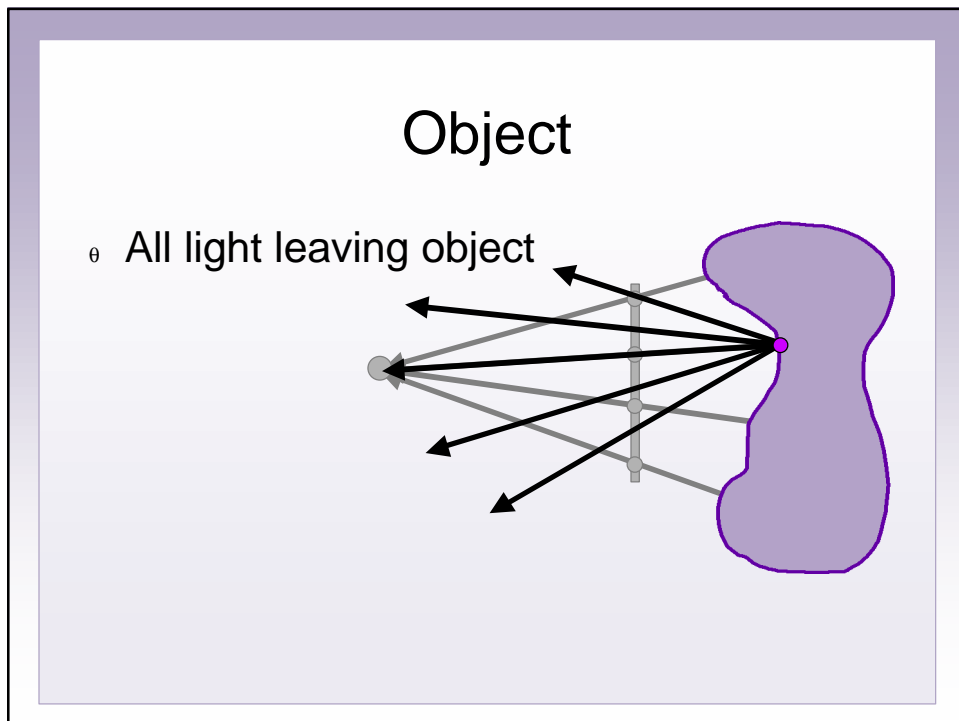
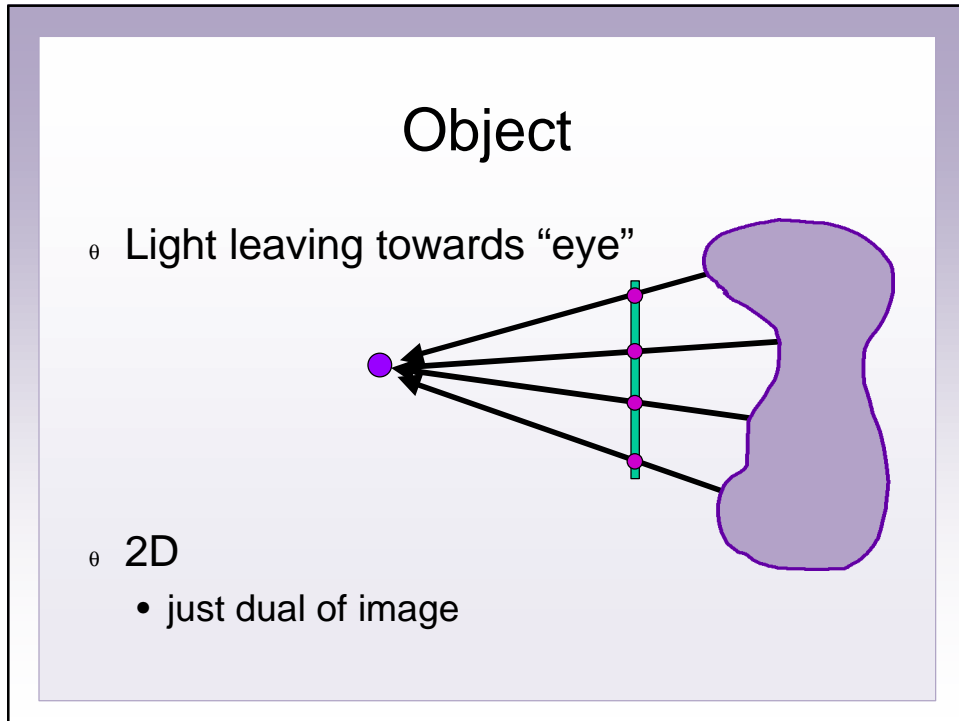


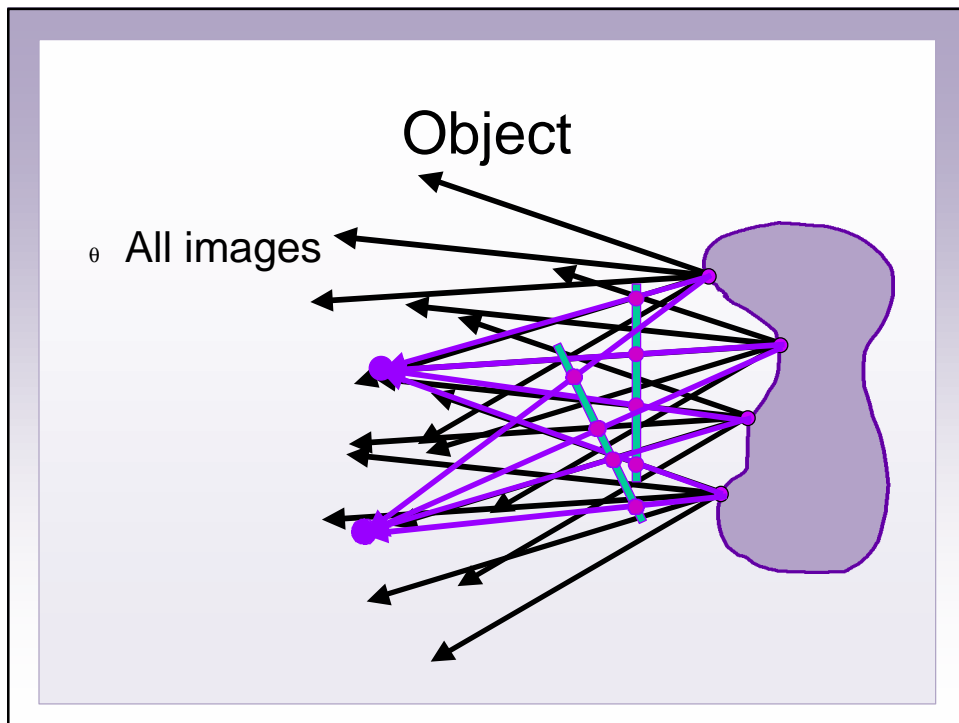
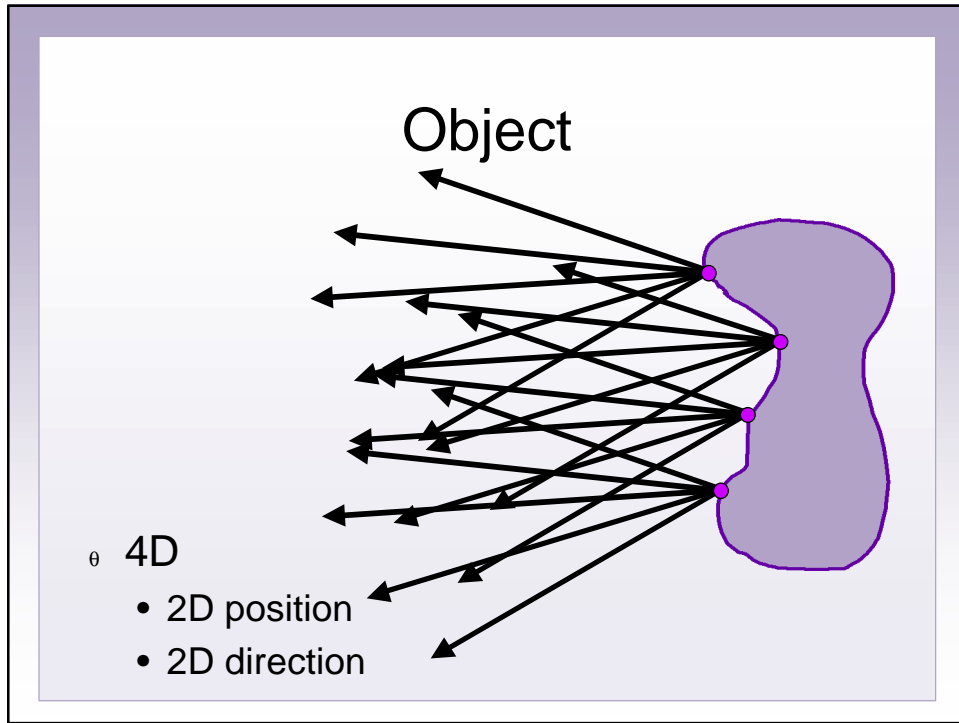


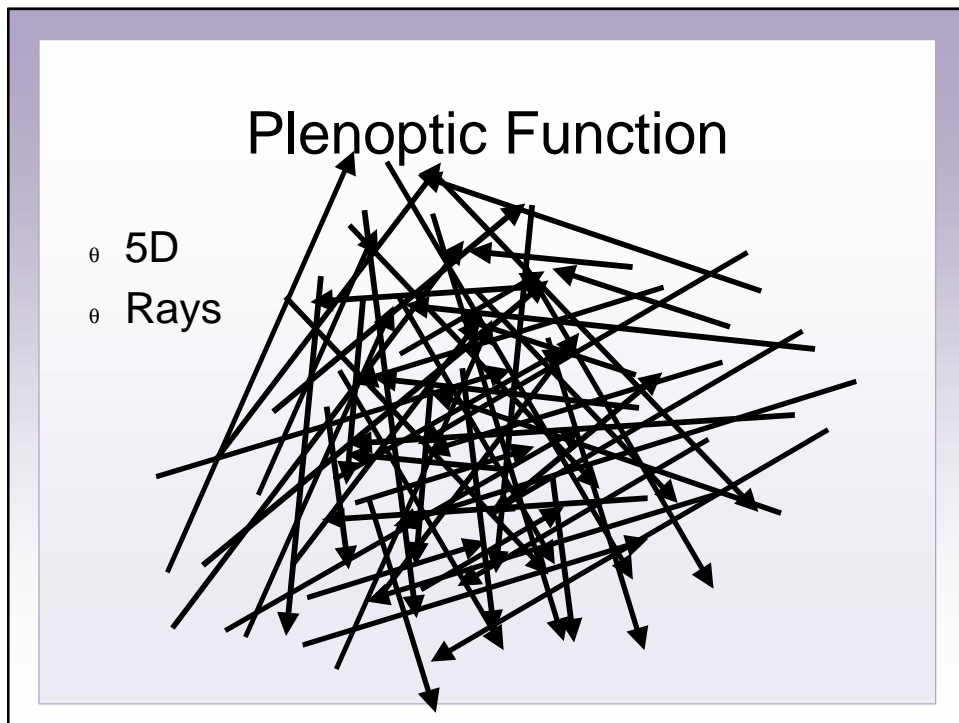
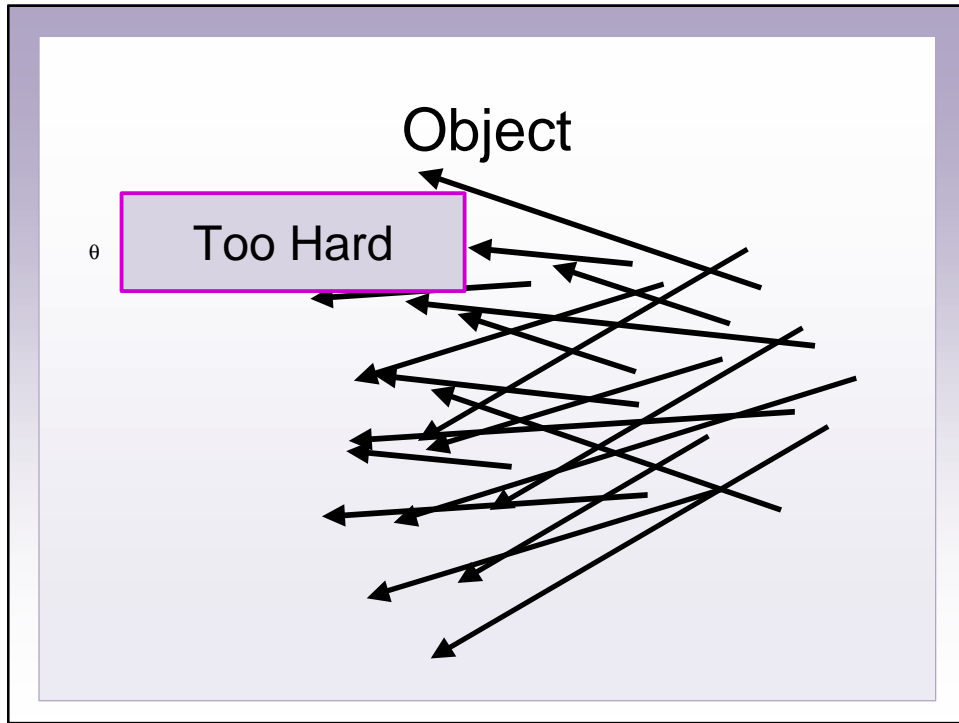


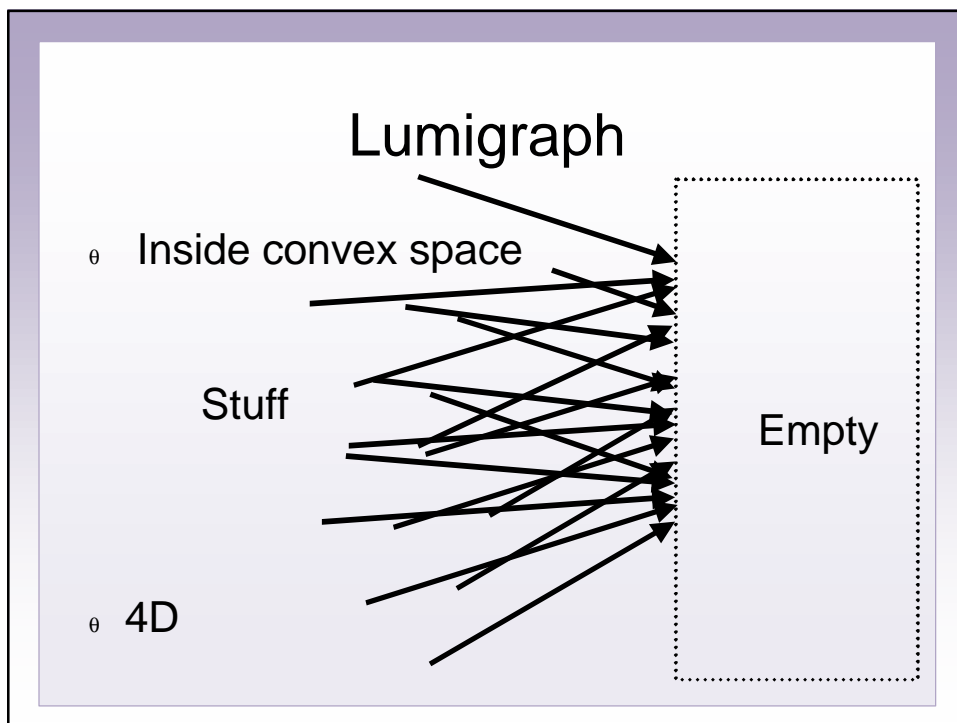
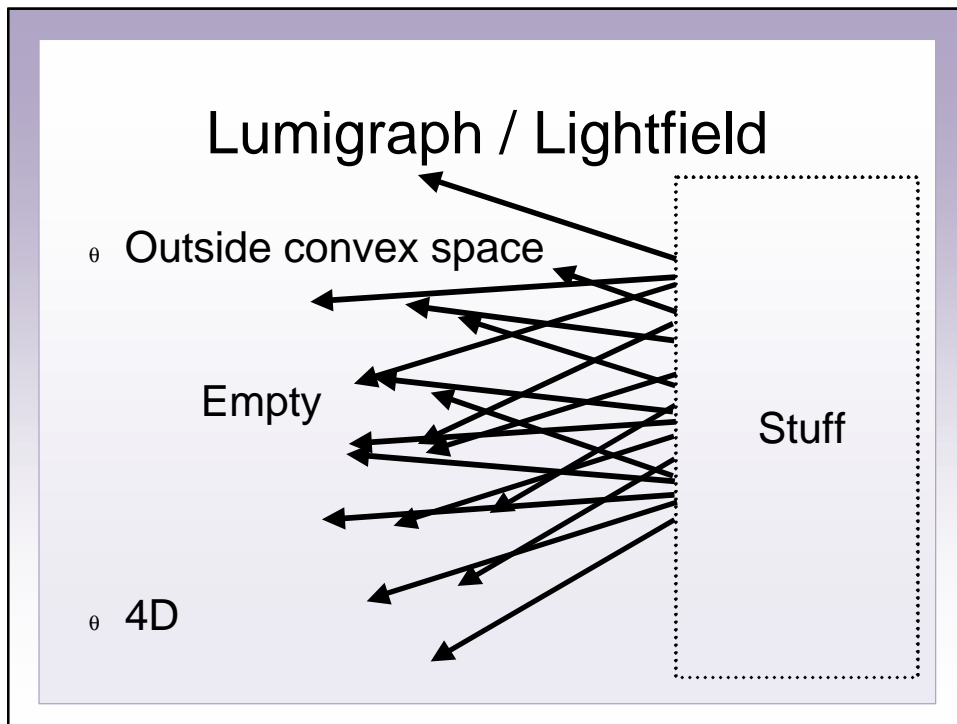


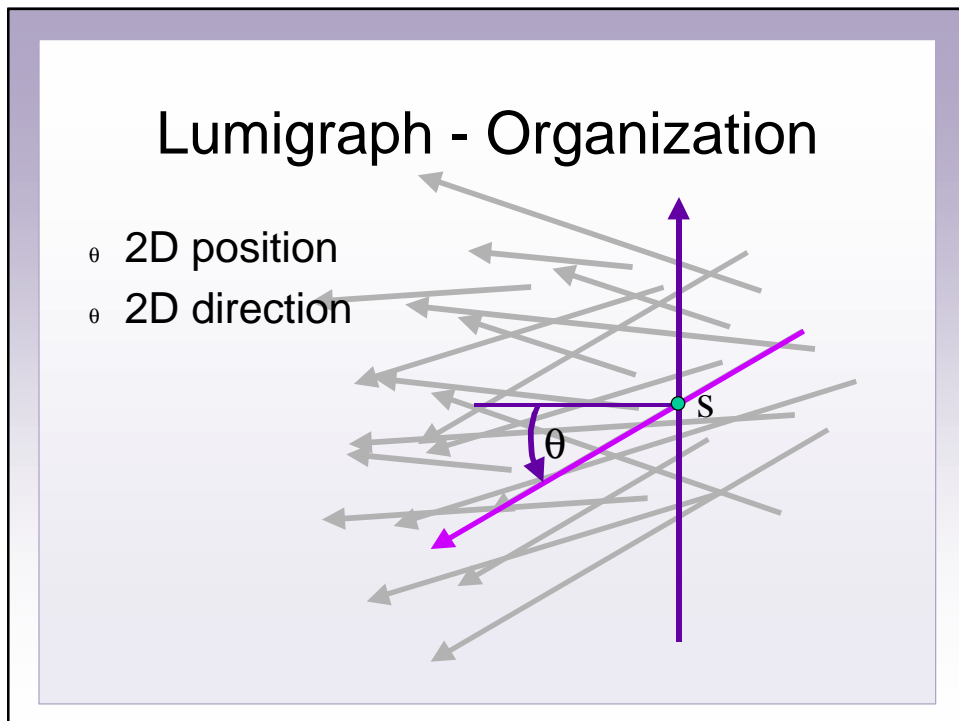
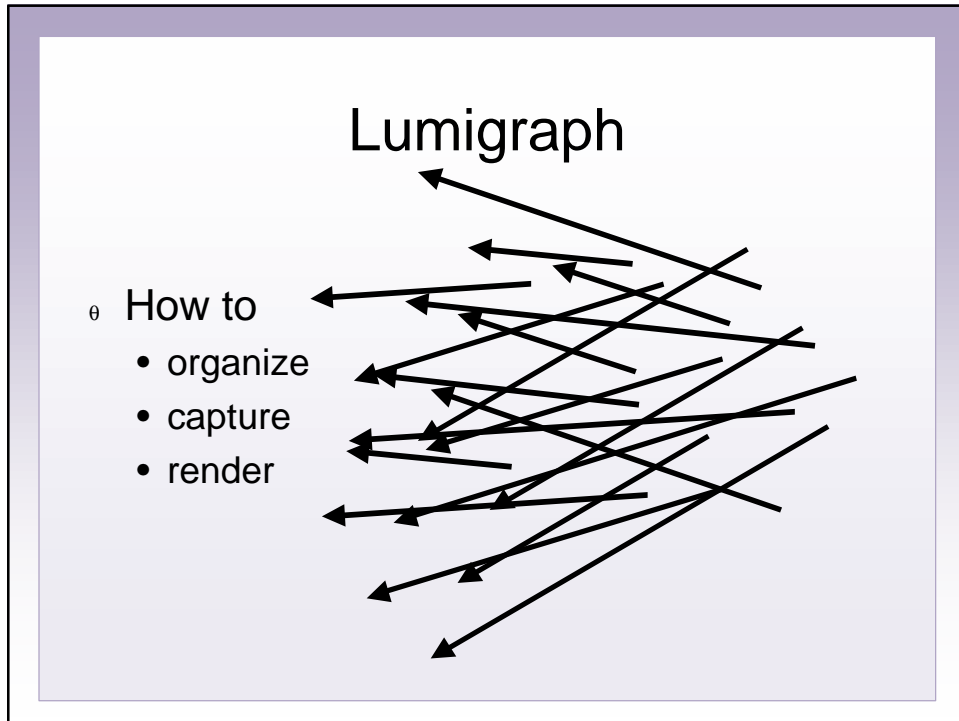


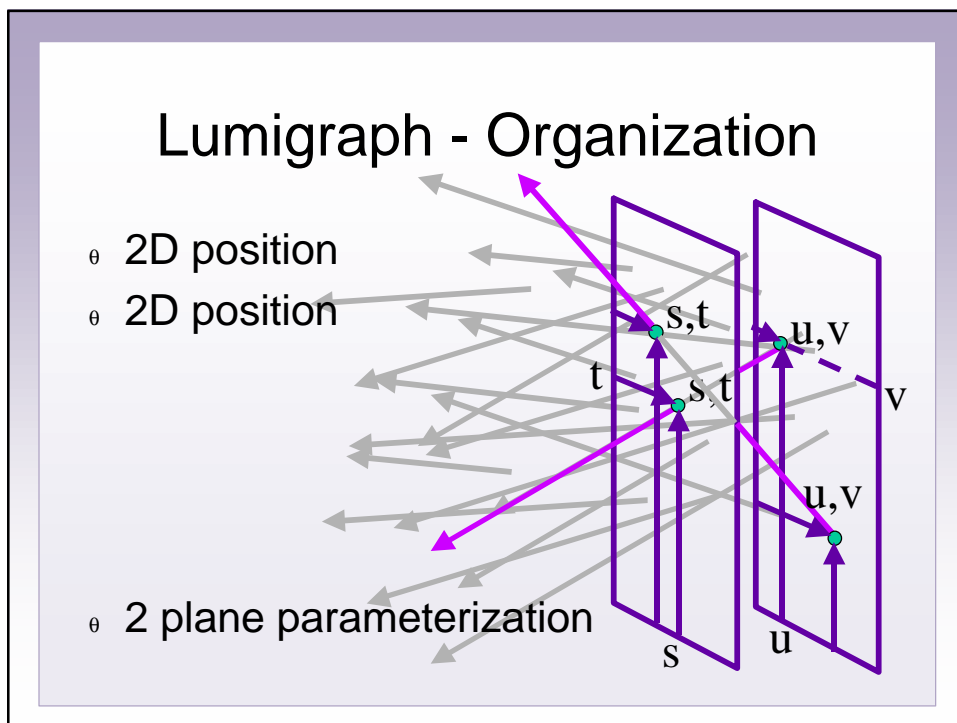
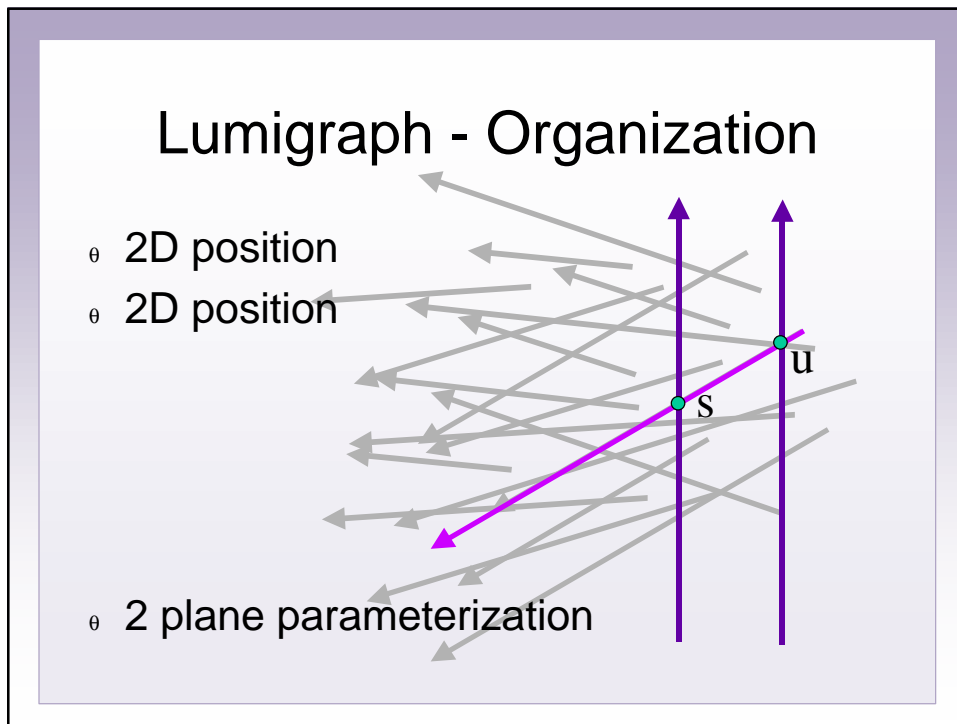






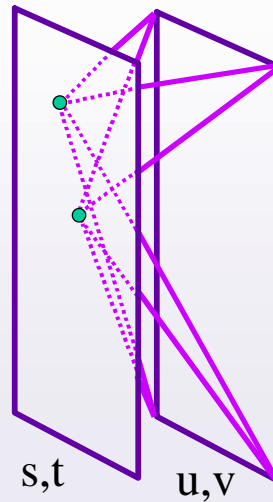






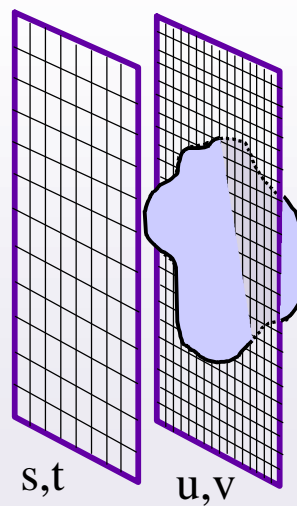
Lumigraph - Organization

- Hold s, t constant
- Let u, v vary
- An image



Lumigraph - Organization

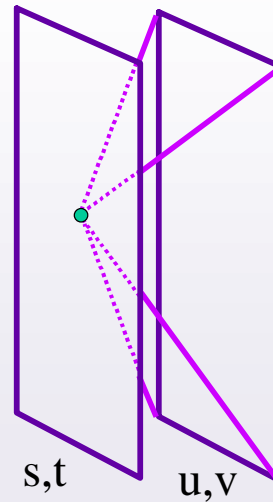
- Discretization
 - higher res near object
 - if diffuse
 - captures texture
 - lower res away
 - captures directions



Lumigraph - Capture

⊖ Idea 1

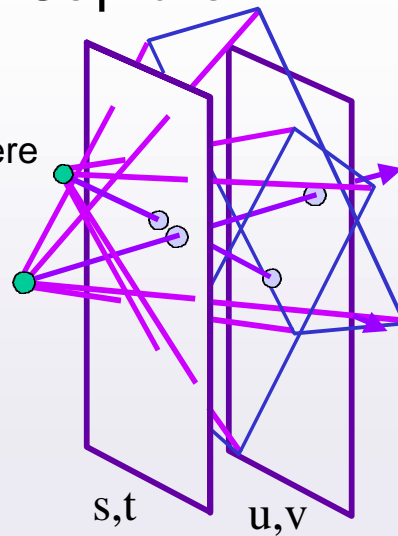
- Move camera carefully over s,t plane
- Gantry
 - see Lightfield paper



Lumigraph - Capture

⊖ Idea 2

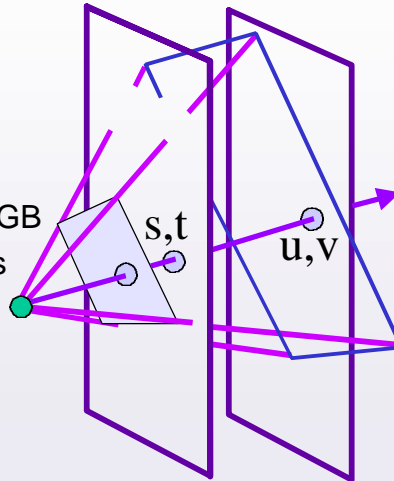
- Move camera anywhere
- Rebinning
 - see Lumigraph paper



Lumigraph - Rendering

• For each output pixel

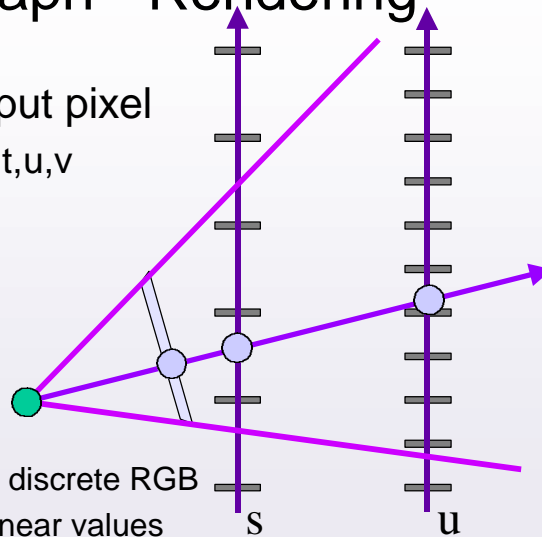
- determine s, t, u, v
- either
 - find closest discrete RGB
 - interpolate near values

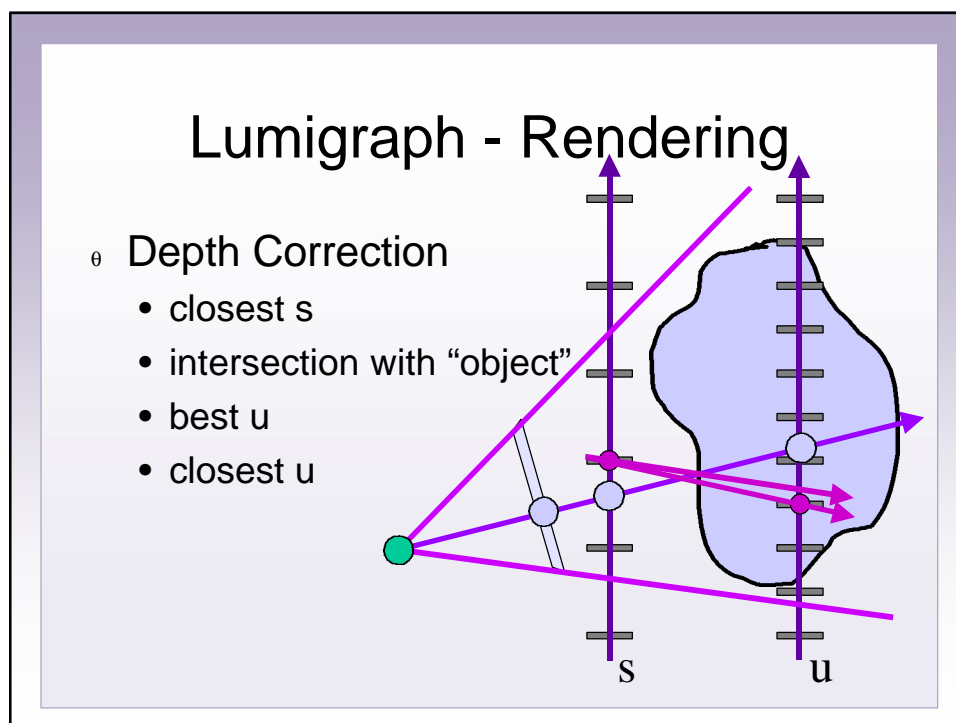
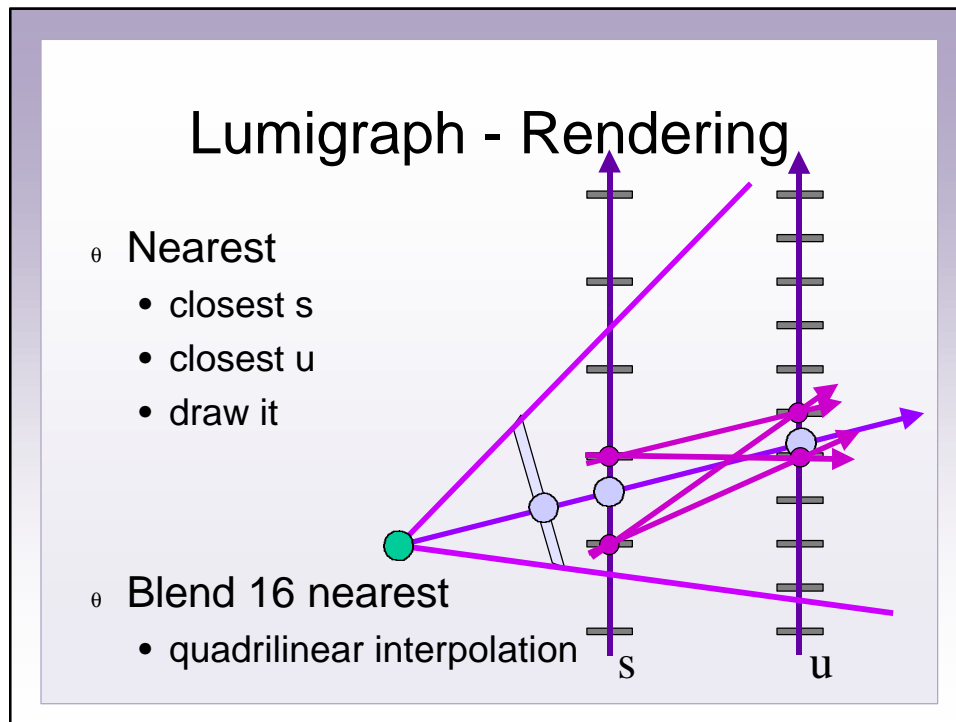


Lumigraph - Rendering

• For each output pixel

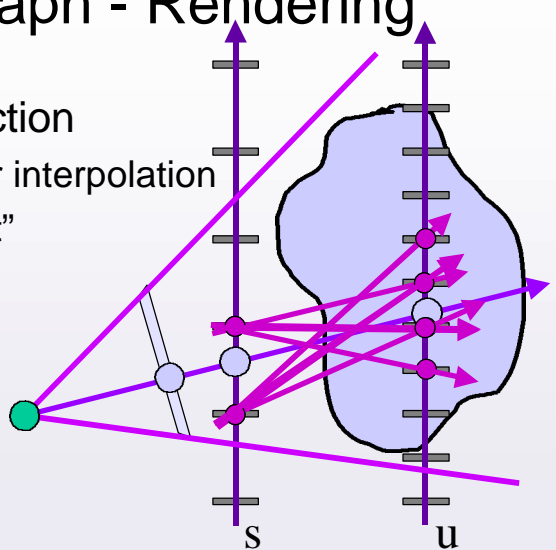
- determine s, t, u, v
- either
 - use closest discrete RGB
 - interpolate near values





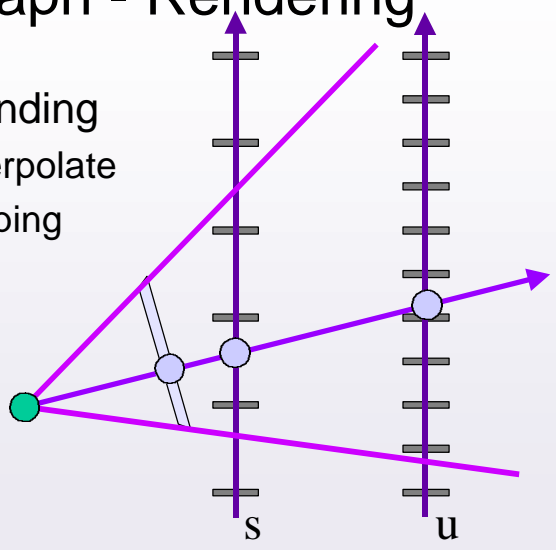
Lumigraph - Rendering

- Depth Correction
 - quadrilinear interpolation
 - new "closest"
 - like focus



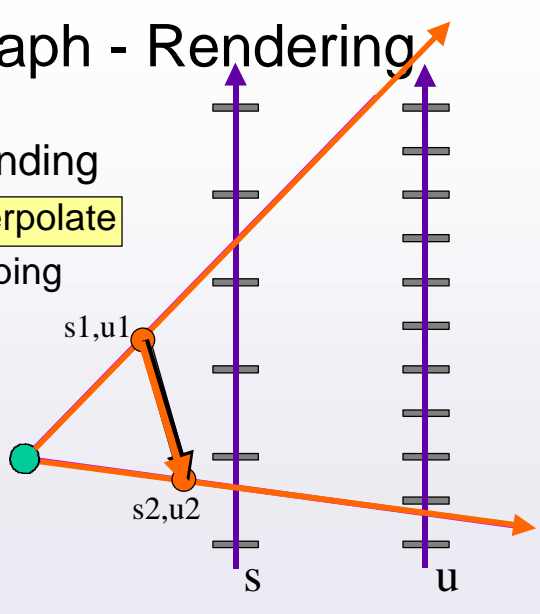
Lumigraph - Rendering

- Fast s,t,u,v finding
 - scanline interpolate
 - texture mapping
 - shear warp



Lumigraph - Rendering

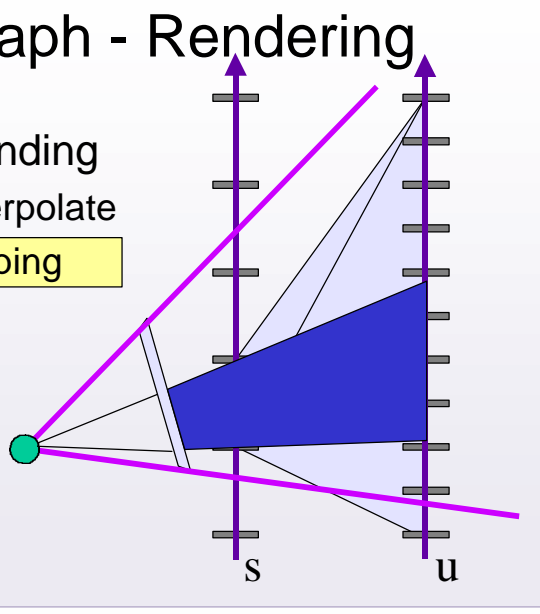
- Fast s,t,u,v finding
 - scanline interpolate
 - texture mapping
 - shear warp



The diagram illustrates the rendering process in the s-u plane. A green dot on the left represents the origin. Two orange lines extend from it, forming a triangle. The top vertex is labeled $s1, u1$ and the bottom vertex is labeled $s2, u2$. Two vertical purple lines with horizontal tick marks represent scanlines. The bottom line is labeled 's' and the top line is labeled 'u'. An orange arrow points from the top vertex towards the right, and another orange arrow points from the bottom vertex towards the right.

Lumigraph - Rendering

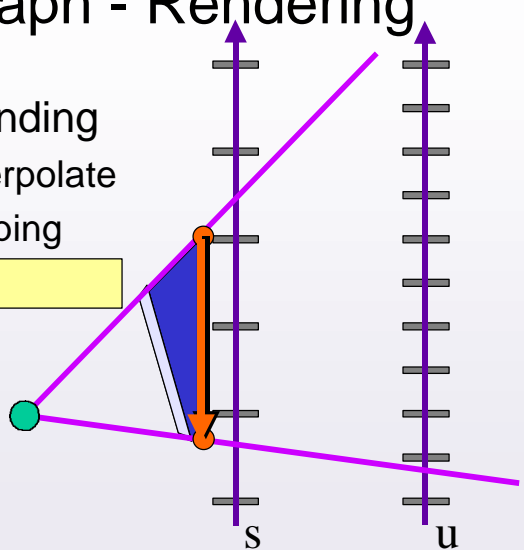
- Fast s,t,u,v finding
 - scanline interpolate
 - texture mapping
 - shear warp



The diagram illustrates the rendering process in the s-u plane. A green dot on the left represents the origin. Two purple lines extend from it, forming a triangle. The top vertex is labeled $s1, u1$ and the bottom vertex is labeled $s2, u2$. Two vertical purple lines with horizontal tick marks represent scanlines. The bottom line is labeled 's' and the top line is labeled 'u'. A blue shaded area is shown between the scanlines, representing the texture mapping. A purple arrow points from the top vertex towards the right, and another purple arrow points from the bottom vertex towards the right.

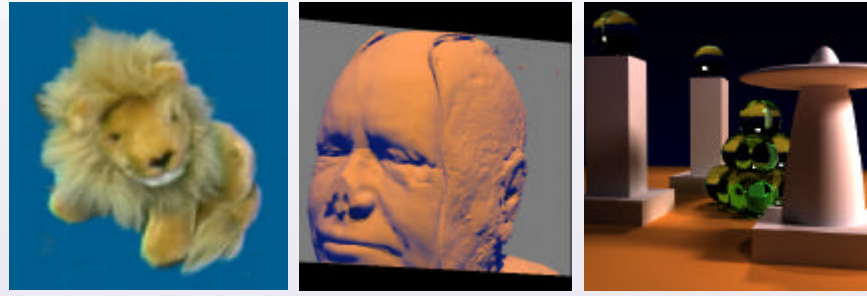
Lumigraph - Rendering

- Fast s,t,u,v finding
 - scanline interpolate
 - texture mapping
 - shear warp



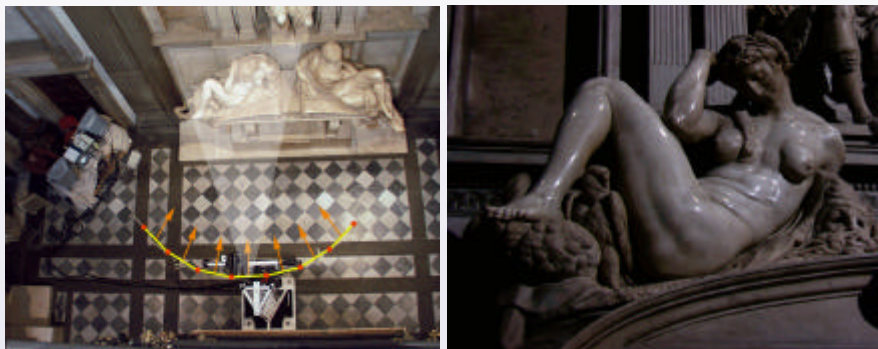
Lumigraph - Demo

- Lumigraph
 - Lion, Fruit Bowl, Visible Woman, Path Tracing



Lightfield - Demo

- ⊖ Digital Michelangelo Project
 - Marc Levoy, Stanford University
 - Lightfield ("night") assembled by Jon Shade

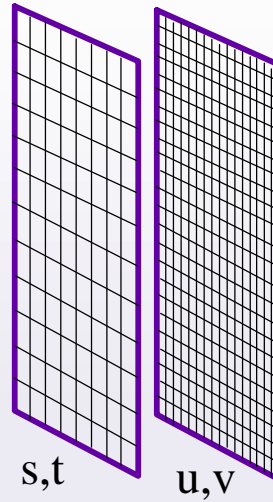


3D Representations

- ⊖ Image is 2D
- ⊖ Lumigraph is 4D
- ⊖ What happened to 3D?
 - 3D Lumigraph subset
 - Concentric mosaics

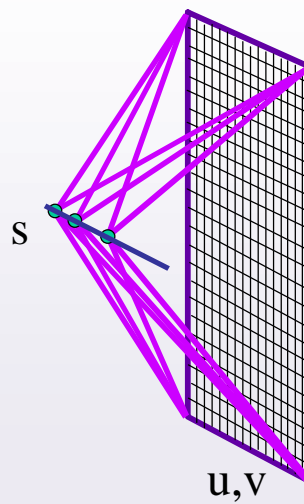
3D Lumigraph

- One row of s,t plane
 - i.e., hold t constant



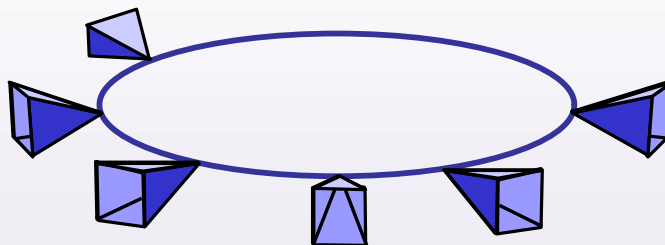
3D Lumigraph

- One row of s,t plane
 - i.e., hold t constant
 - thus s,u,v
 - a "row of images"



Concentric Mosaics

- Replace “row” with “circle” of images

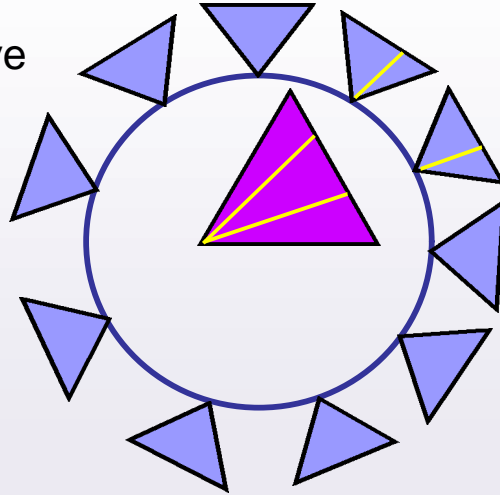


Concentric Mosaics



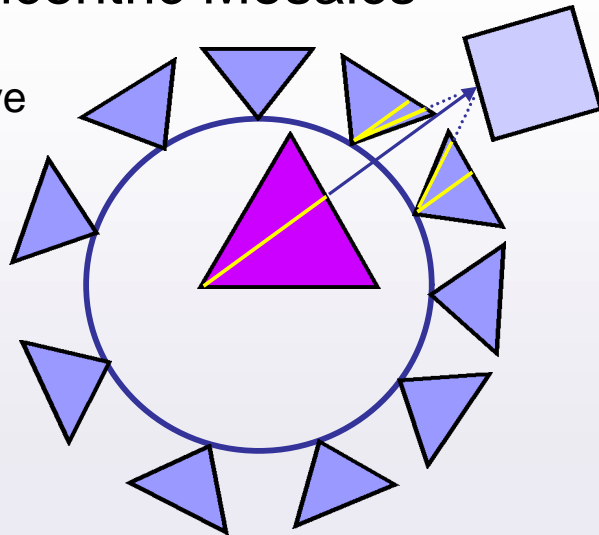
Concentric Mosaics

From above



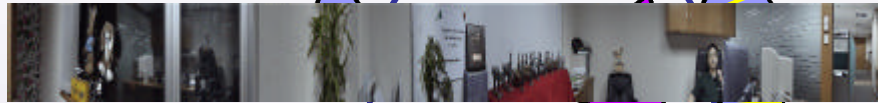
Concentric Mosaics

From above



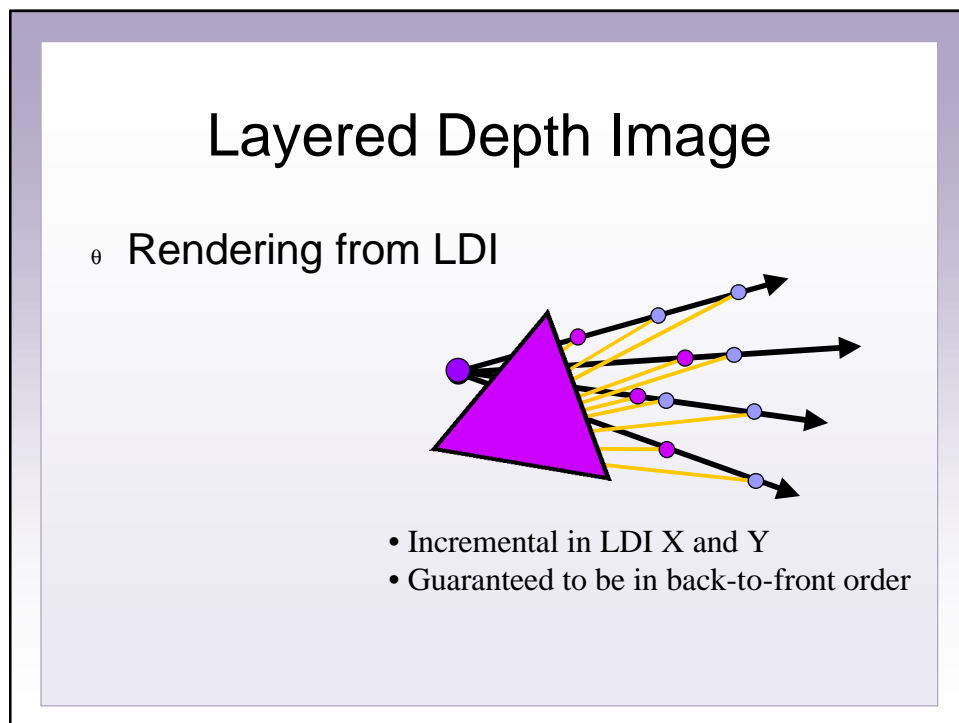
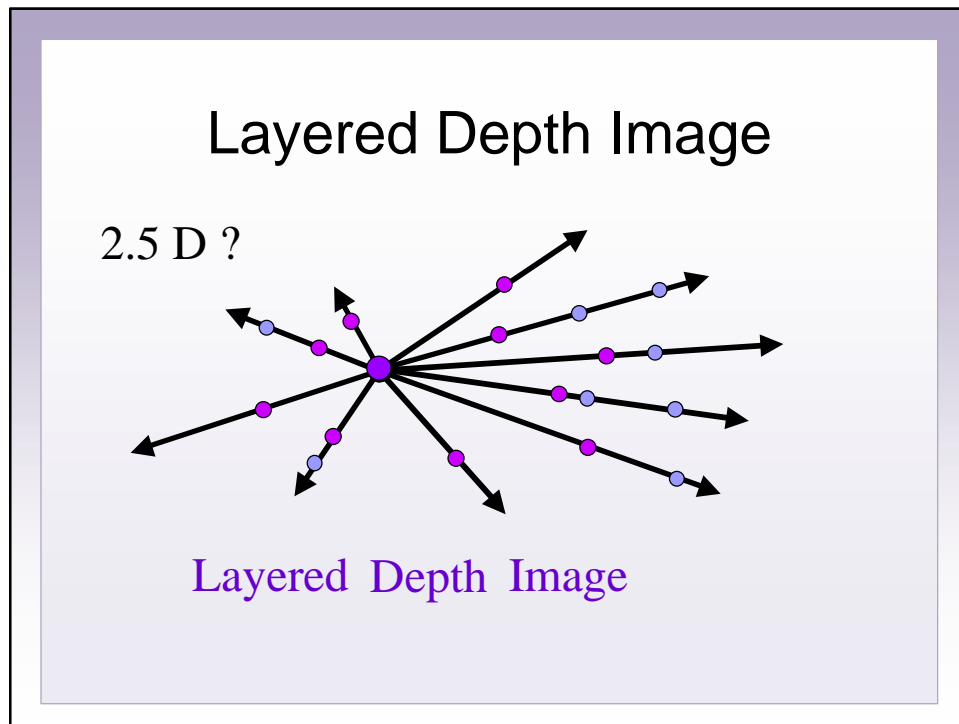
Concentric Mosaics

- Panorama



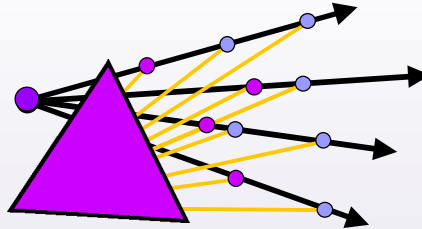
2.5D Representations

- Image is 2D
- Lumigraph is 4D
- 3D
 - 3D Lumigraph subset
 - Concentric mosaics
- 2.5D
 - Layered Depth Images
 - View Dependent Surfaces



Layered Depth Image

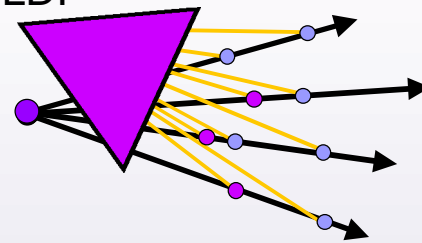
Rendering from LDI



- Incremental in LDI X and Y
- Guaranteed to be in back-to-front order

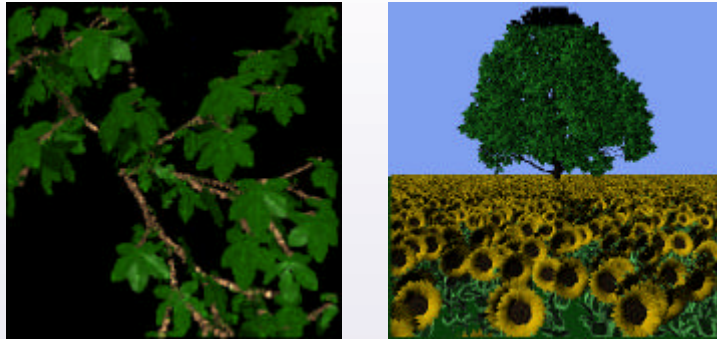
Layered Depth Image

Rendering from LDI



- Incremental in LDI X and Y
- Guaranteed to be in back-to-front order

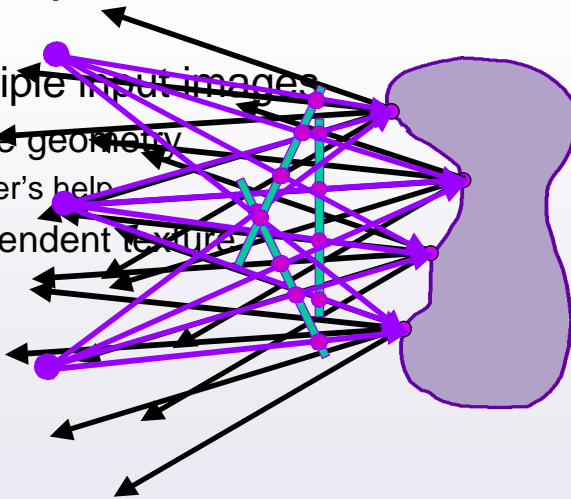
Layered Depth Image



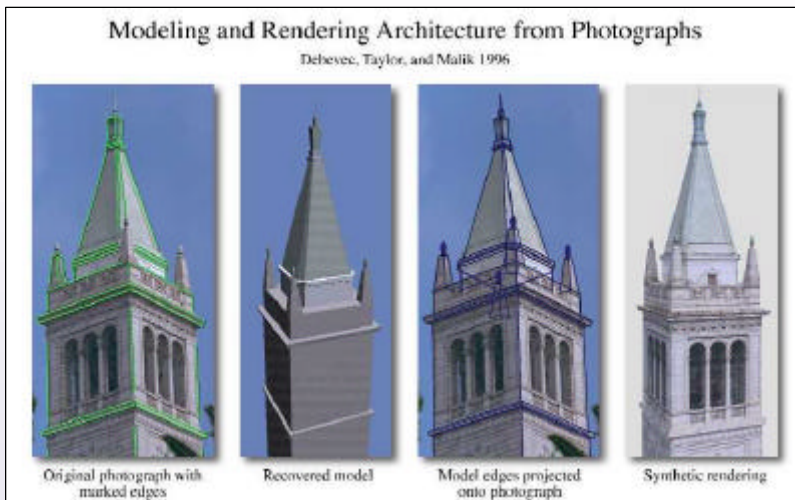
View Dependent Surfaces

From multiple input images

- determine geometry
 - with user's help
- view dependent texture



View Dependent Surfaces



Summary

- ⊖ 5D: Plenoptic Function (Ray)
- ⊖ 4D: Lumigraph / Lightfield
- ⊖ 3D: Lumigraph Subset
- ⊖ 3D: Concentric Mosaics
- ⊖ 2.5D: Layered Depth Image
- ⊖ 2.5D: View Dependent Models
- ⊖ 2D: Image

Thanks

- ⊖ Peter-Pike Sloan (Lumigraph)
- ⊖ Jonathan Shade (Lightfield, LDI)
- ⊖ Marc Levoy, Stanford University
 - Michaelangelo data set